

# Logics for Continuous Reachability in Petri Nets and Vector Addition Systems with States

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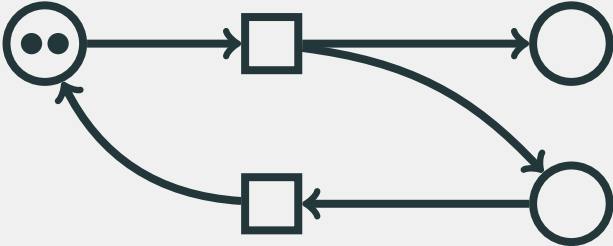
Michael Blondin



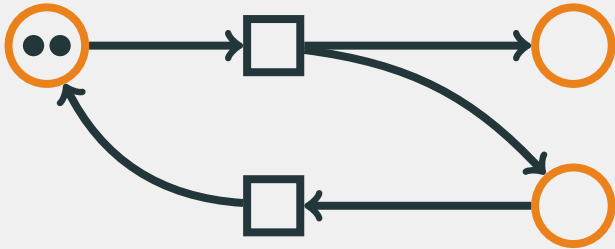
Christoph Haase



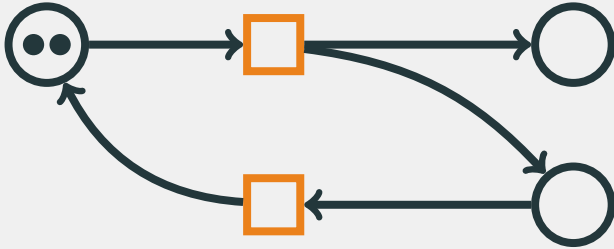
# Petri nets



# Petri nets

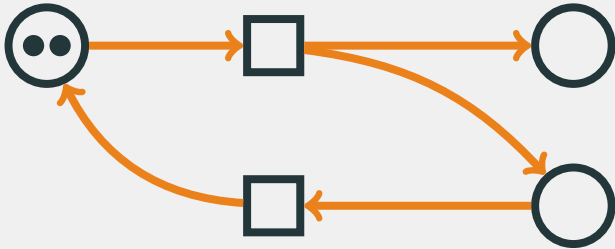


*Places*



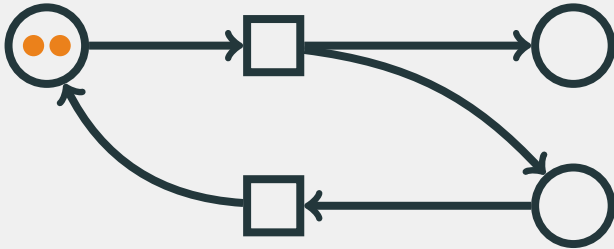
*Transitions*

# Petri nets



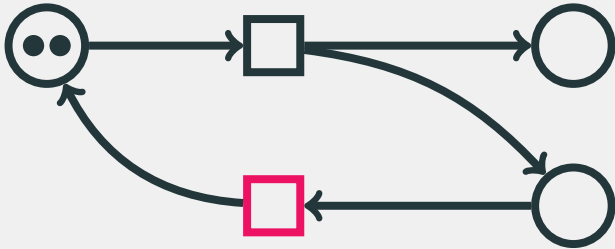
*Arcs*

# Petri nets



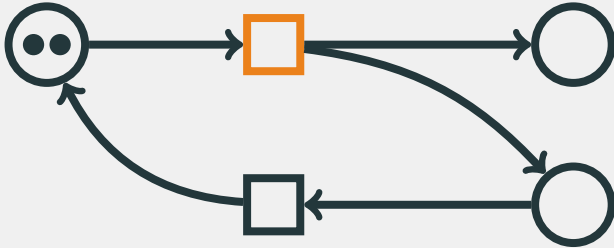
*Tokens*

# Petri nets



*Disabled*

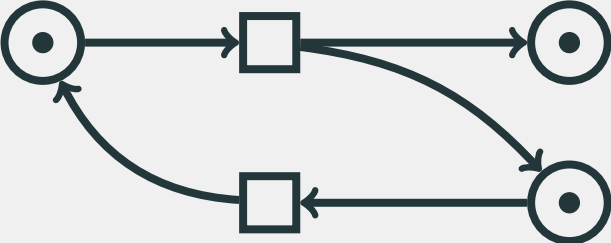
# Petri nets



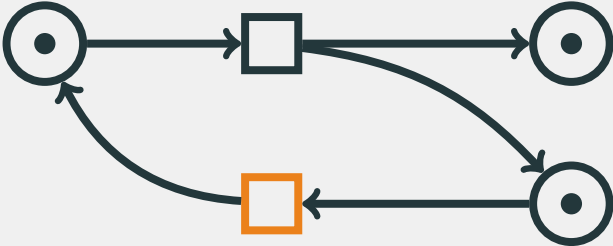
*Enabled*



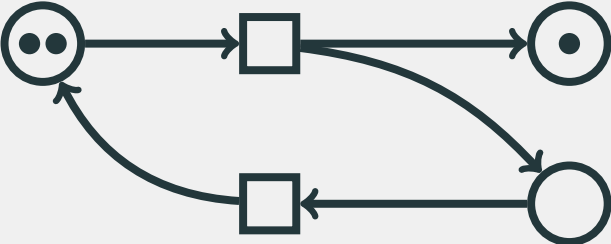
# Petri nets



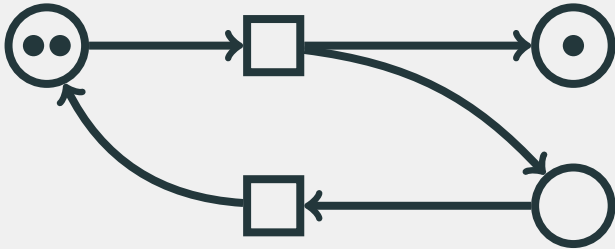
# Petri nets



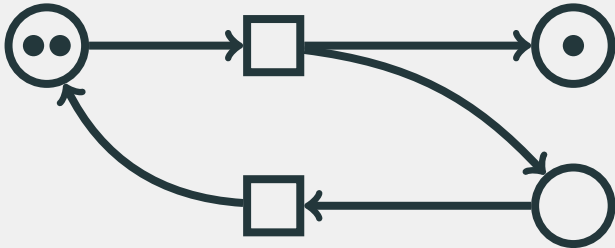
# Petri nets



# Petri nets



$$(2, 0, 0) \xrightarrow{*}_{\mathbb{N}} (2, 1, 0)$$



Reachability:  $\mathbf{u} \xrightarrow{*} \mathbb{N} \mathbf{v}$ ?

# Petri nets

Concurrent programs

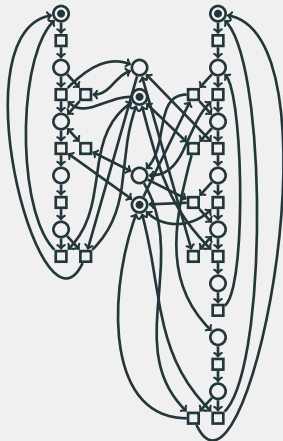
Protocols

Business processes

Biological processes

⋮

correct? →



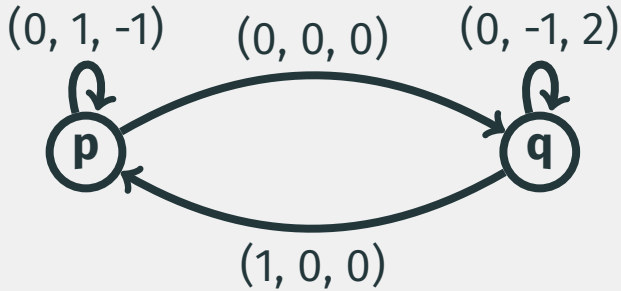
Reachability:  $\mathbf{u} \xrightarrow{*} \mathbb{N} \mathbf{v}$ ?

## Verifying multi-threaded programs

Counters: number of threads

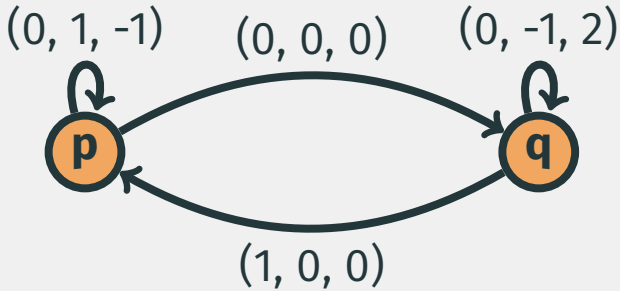
States: shared resources

## Petri nets / Vector addition systems with states (VASS)



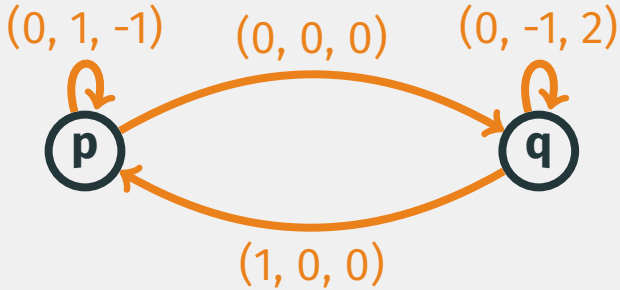


# Petri nets / Vector addition systems with states (VASS)



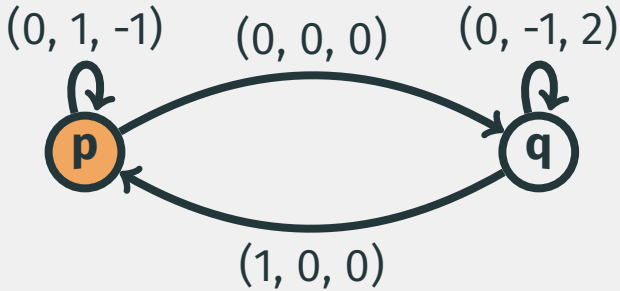
*Control-states*

# Petri nets / Vector addition systems with states (VASS)



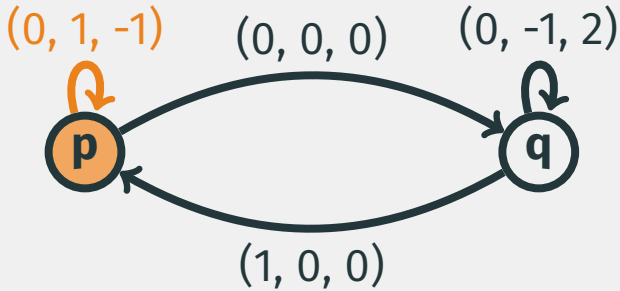
Transitions

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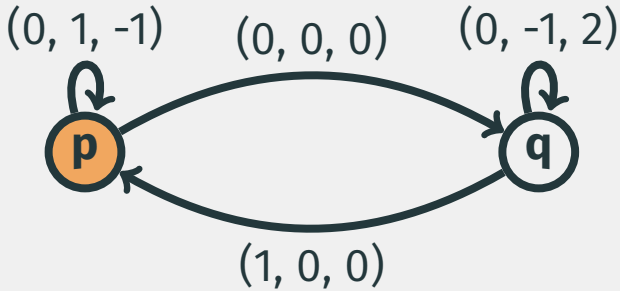
$p(0, 0, 1)$

# Petri nets / Vector addition systems with states (VASS)



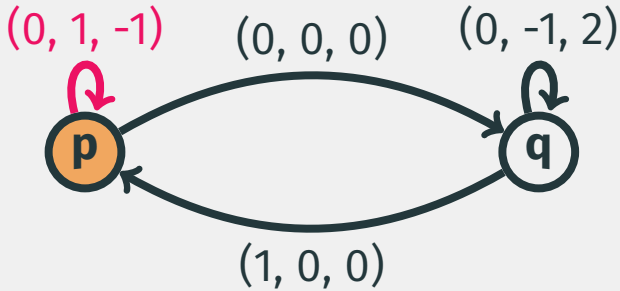
**$p(0, 0, 1)$**

# Petri nets / Vector addition systems with states (VASS)



$p(0, 1, 0)$

# Petri nets / Vector addition systems with states (VASS)



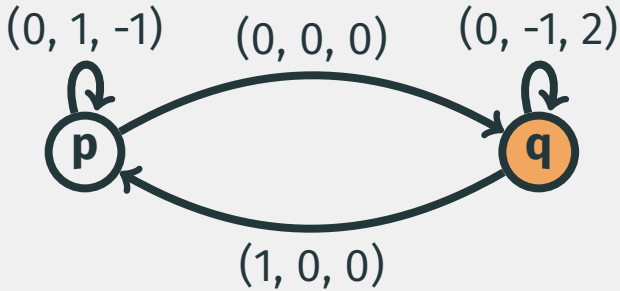
**$p(0, 1, 0)$**

# Petri nets / Vector addition systems with states (VASS)



**$p(0, 1, 0)$**

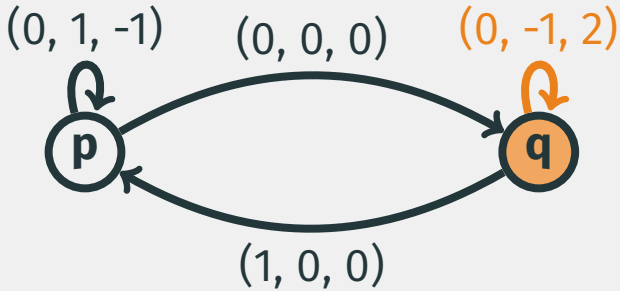
# Petri nets / Vector addition systems with states (VASS)



$q(0, 1, 0)$

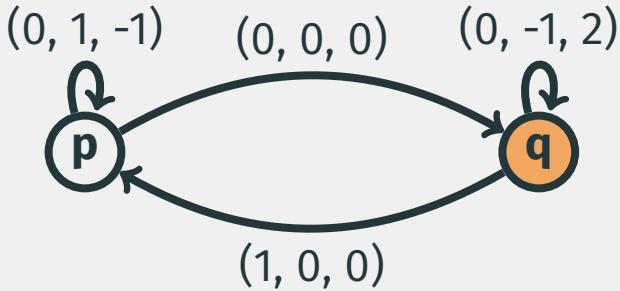


# Petri nets / Vector addition systems with states (VASS)



**$q(0, 1, 0)$**

# Petri nets / Vector addition systems with states (VASS)



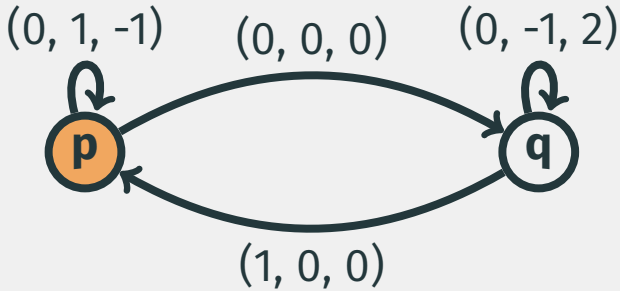
$q(0, 0, 2)$

# Petri nets / Vector addition systems with states (VASS)



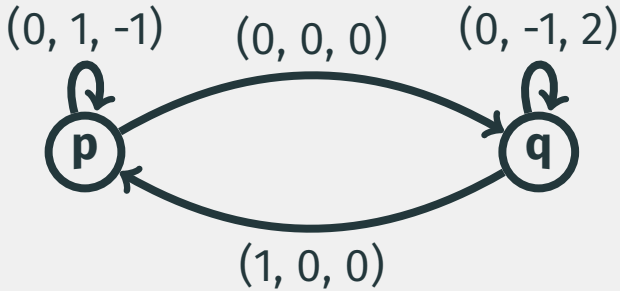
**$q(0, 0, 2)$**

# Petri nets / Vector addition systems with states (VASS)



**$p(1, 0, 2)$**

# Petri nets / Vector addition systems with states (VASS)



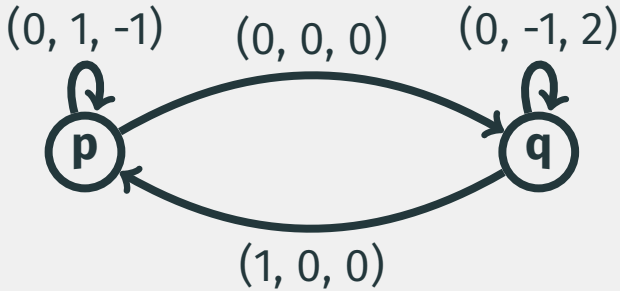
$$p(0, 0, 1) \xrightarrow{*}_{\mathbb{N}} p(1, 0, 2)$$

## Petri nets / Vector addition systems with states (VASS)



$$p(0, 0, 1) \xrightarrow{*}_{\mathbb{N}} p(x, y, z) \iff 0 < y + z \leq 2^x$$

# Petri nets / Vector addition systems with states (VASS)

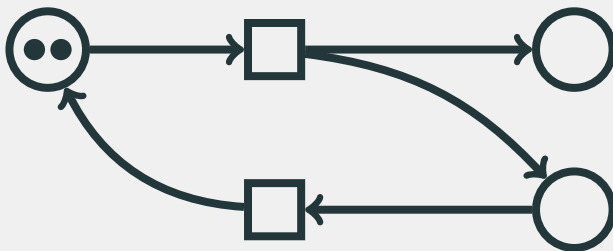


Reachability:  $p(\mathbf{u}) \xrightarrow{*}_{\mathbb{N}} q(\mathbf{v})$  ?

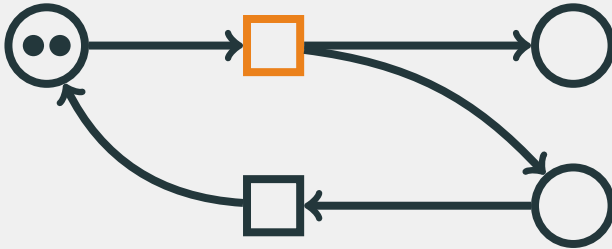
Reachability is...

- equivalent for Petri nets and VASS
- **not expressible** in  $\text{FO}(\mathbb{N}, +, <)$
- **EXPSpace-hard** (Lipton '76)
- solvable in **cubic-Ackermannian time**  
(Leroux and Schmitz LICS'15)

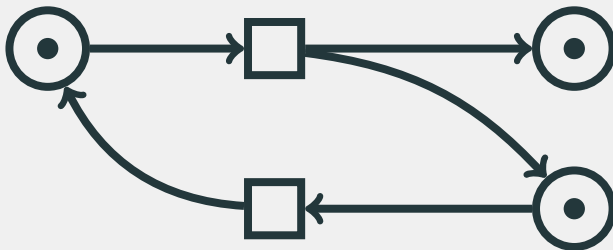




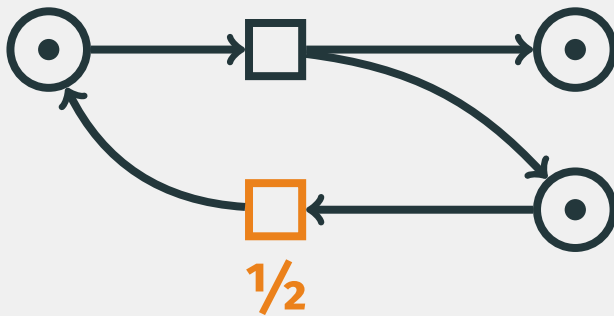
Can fire transitions  
fractionally



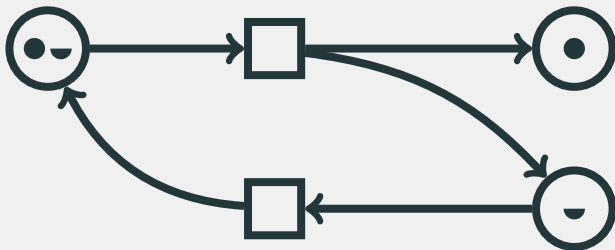
Can fire transitions  
fractionally



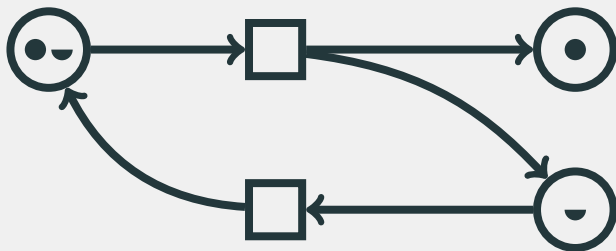
Can fire transitions  
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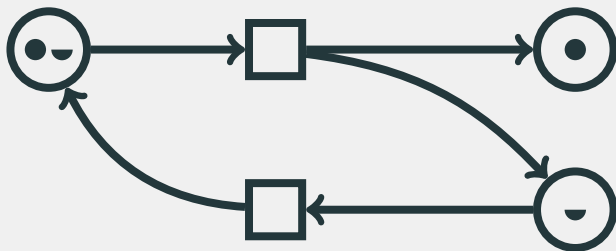
Can fire transitions  
fractionally



Can fire transitions  
fractionally



$$(2, 0, 0) \xrightarrow{*} \mathbb{Q}_+ (1\frac{1}{2}, 1, \frac{1}{2})$$



Continuous  
reachability:  $\mathbf{u} \xrightarrow{*} \mathbb{Q}_+ \mathbf{v}?$

Continuous reachability is...

- an **over-approximation**:

$$\neg(\mathbf{u} \xrightarrow{*}_{\mathbb{Q}_+} \mathbf{v}) \text{ implies } \neg(\mathbf{u} \xrightarrow{*}_{\mathbb{N}} \mathbf{v})$$

- **PTIME-complete** (Fracca and Haddad PN'13)
- **expressible in  $\exists \text{FO}(\mathbb{Q}_+, +, <)$**   
(B., Finkel, Haase and Haddad TACAS'16)



Continuous reachability is...

- an over-approximation

*fast with SMT solver  
...but NP-complete*

- PTIME-complete



- expressible in  $\exists \text{FO}(\mathbb{Q}_+, +, <)$

Continuous reachability is...

- an over-approximation

*often good*  
*...but no control-states*

- PTIME-complete
- expressible in  $\exists \text{FO}(\mathbb{Q}_+, +, <)$

new fragment of  $\exists \text{FO}(\mathbb{Q}_+, +, <)$

- PTIME-complete
- equivalent to Petri net continuous reachability

new model: continuous VASS

- with control-states
- with reachability equivalent to  $\exists \text{FO}(\mathbb{Q}, +, <)$

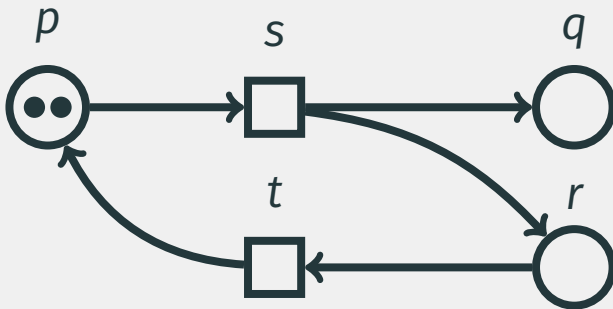
new fragment of  $\exists \text{FO}(\mathbb{Q}_+, +, <)$

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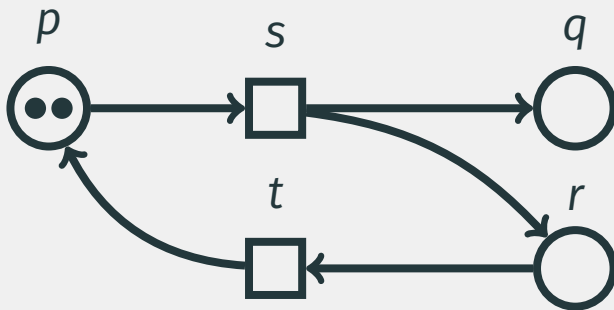
- with control-states
- with reachability equivalent to  $\exists \text{FO}(\mathbb{Q}, +, <)$

## Expressing continuous reachability



$y$  reachable  $\iff \exists$  Parikh vector  $\pi$  s.t.

## Expressing continuous reachability

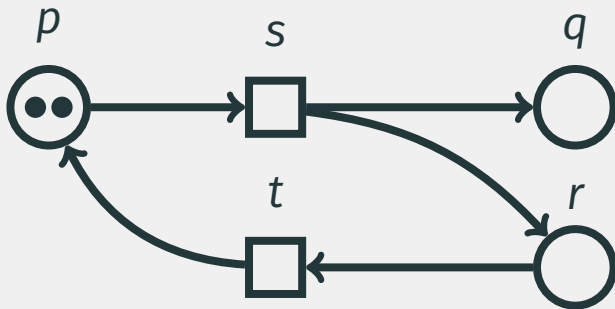


$\mathbf{y}$  reachable  $\iff \exists$  Parikh vector  $\pi$  s.t.

$$\text{a) } \mathbf{y}(p) = 2 - \pi(s) + \pi(t) \quad \mathbf{y}(q) = \pi(s)$$

$$\mathbf{y}(r) = \pi(s) + \pi(t)$$

## Expressing continuous reachability

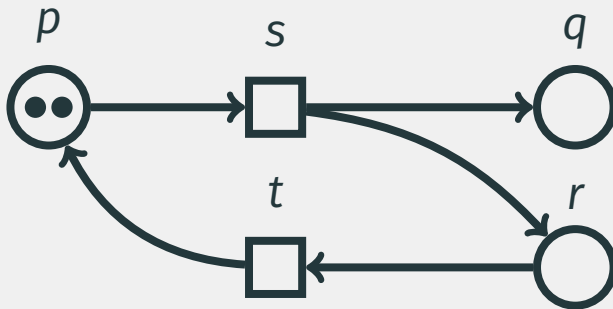


$\mathbf{y}$  reachable  $\iff \exists$  Parikh vector  $\pi$  s.t.

b)  $\{u : \pi(u) > 0\}$  firable from  $(2, 0, 0)$

c)  $\{u : \pi(u) > 0\}$  firable to  $\mathbf{y}$

## Expressing continuous reachability



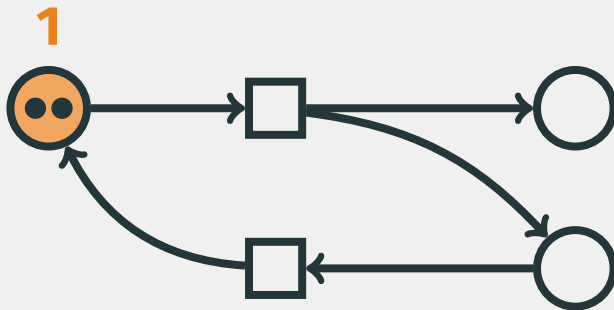
linear size  $\exists \text{FO}(\mathbb{Q}_+, +, \langle \rangle)$  formula

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# Expressing continuous reachability

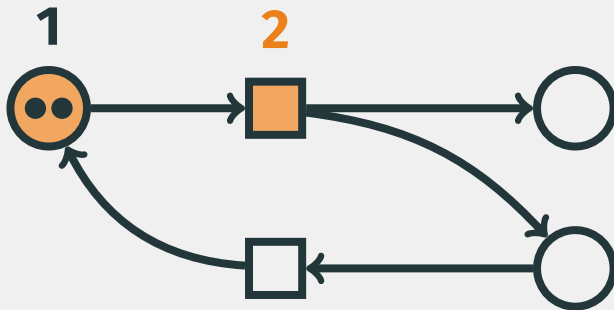


linear size  $\exists \text{FO}(\mathbb{Q}_+, +, \langle) \text{ formula}$

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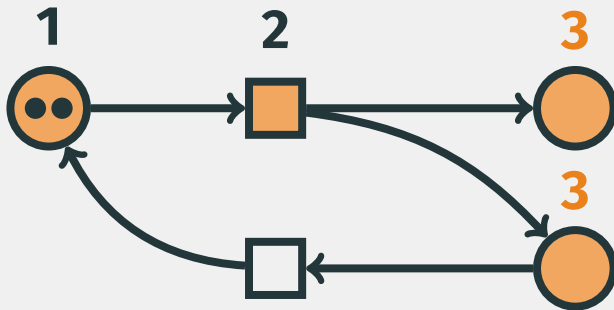


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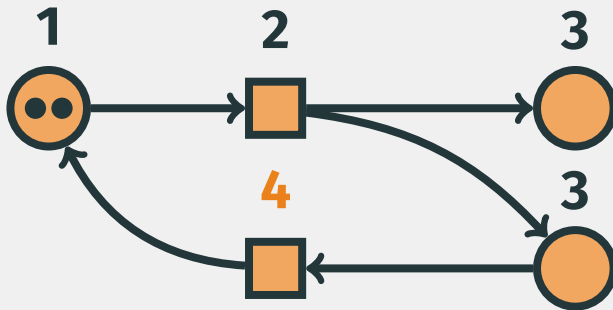


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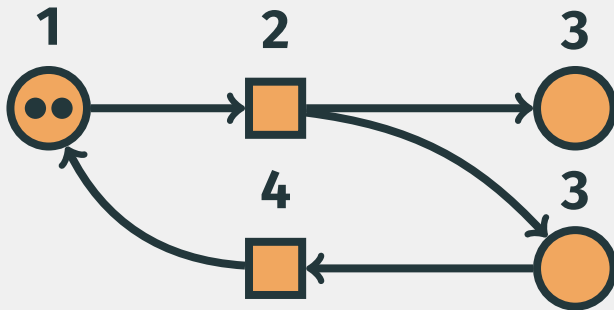


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## Expressing continuous reachability



linear size  $\exists \text{FO}(\mathbb{Q}_+, +, <)$  formula

*NP-complete*

Conjunction of terms of the form

$$a_1 \cdot x_1 + \dots + a_n \cdot x_n \sim c \vee \bigvee_{1 \leq i \leq m} \bigwedge_{j \in J_i} x_j > 0$$

## Convex linear Horn constraints

Conjunction of terms of the form

$$a_1 \cdot x_1 + \dots + a_n \cdot x_n \sim c \vee \bigvee_{1 \leq i \leq m} \bigwedge_{j \in J_i} x_j > 0$$

variables over  $\mathbb{Q}_+$

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variables over  $\mathbb{Q}_+$

coeff. in  $\mathbb{Z}$



## Convex linear Horn constraints

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variables over  $\mathbb{Q}_+$

coeff. in  $\mathbb{Z}$

$\sim$  is  $\geq$  or  $>$

## Convex linear Horn constraints

Examples :

$$x = 0 \quad \equiv \quad -x \geq 0$$

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$$x > 0 \rightarrow \bigvee_{y \in Y} y > 0 \quad \equiv \quad x = 0 \vee \bigvee_{y \in Y} y > 0$$

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$$x > 0 \leftarrow \bigvee_{y \in Y} y > 0 \quad \equiv \quad \bigwedge_{y \in Y} (y = 0 \vee x > 0)$$

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$$x > 0 \leftarrow \bigwedge_{y \in Y} y > 0 \quad \equiv \quad \text{not expressible}$$

Examples :

- graph reachability
- strong connectivity (from a node)

in subgraph  $G[u : \mathbf{x}_u > 0]$

# Convex linear Horn constraints

## Theorem

Continuous Petri net reachability is expressible by a quadratic size formula

## Proof idea

$$\mathbf{x} + \mathbf{C} \cdot \boldsymbol{\pi} = \mathbf{y} \wedge \text{firability constraints}$$



# Convex linear Horn constraints

## Theorem

Satisfiability is PTIME-complete

## Proof idea

- $\in$  PTIME: algorithm exploiting convexity
- Hardness: from linear prog. feasibility

Related work:

CSP of linear Horn constraints

(Jonsson and Backström '98

Koubarakis '01)

## Convex linear Horn constraints

Related work:

*incomparable*

CSP of linear Horn constraints

(Jonsson and Backström '98  
Koubarakis '01)

### Theorem

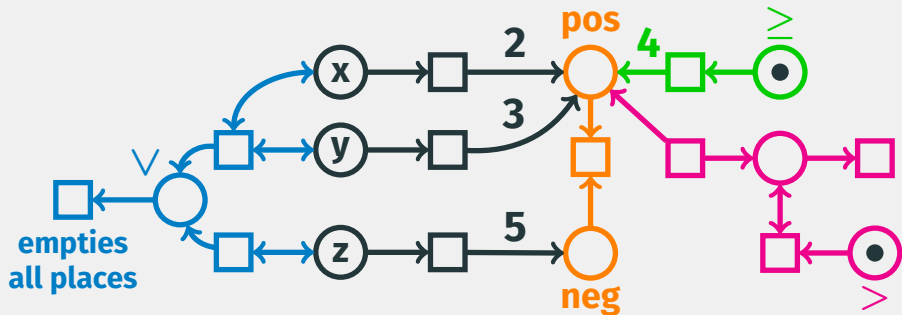
Convex linear Horn constraints solutions  
are expressible as  
reachability sets of continuous Petri nets

## Solutions as reachability sets

$$2x + 3y - 5z > -4 \vee (x > 0 \wedge y > 0) \vee z > 0$$

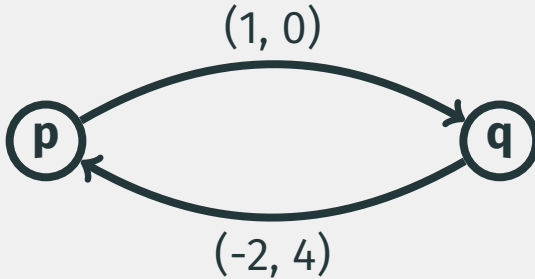


all places can be emptied



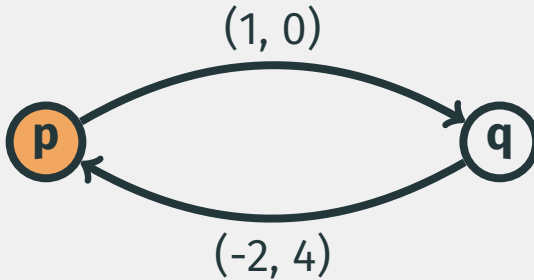
# Continuous VASS:

- Hybrid model
- subsume continuous Petri nets



Transitions can be scaled  
by  $0 < x \leq 1$

# Continuous VASS



$p(0, 0)$

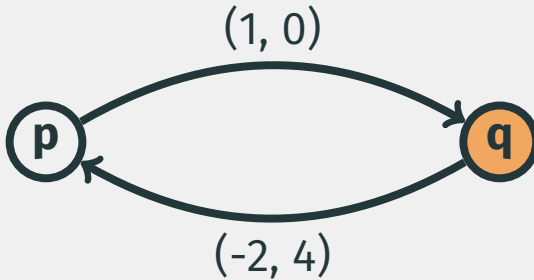


# Continuous VASS



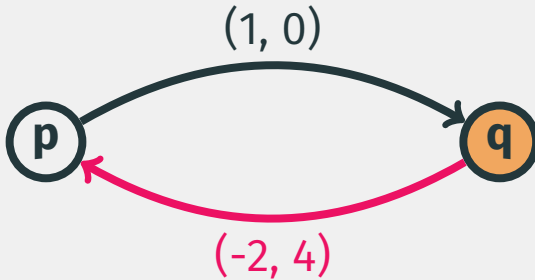
**$p(0, 0)$**

# Continuous VASS



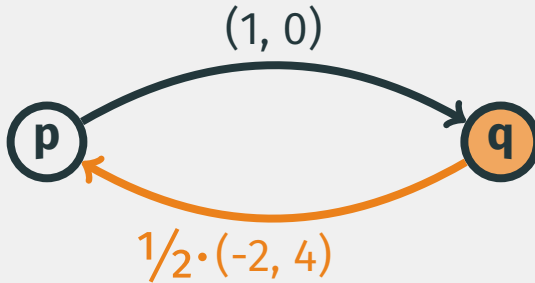
$q(1, 0)$

# Continuous VASS



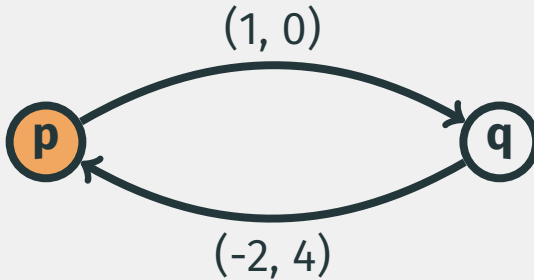
$q(1, 0)$

# Continuous VASS



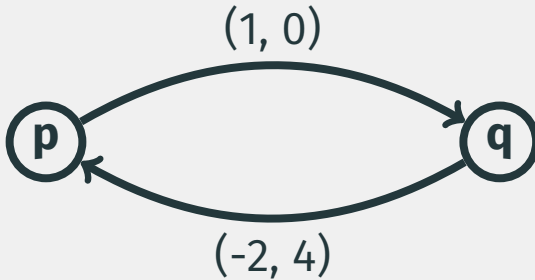
**$q(1, 0)$**

# Continuous VASS

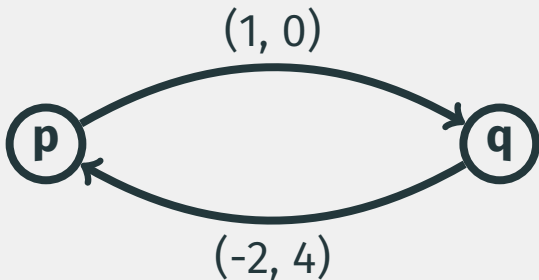


$p(0, 2)$

# Continuous VASS



$$p(0, 0) \xrightarrow{*} \mathbb{Q}_+ \quad q(0, 2)$$



Reachability:  $p(\mathbf{u}) \xrightarrow{*} \mathbb{Q}_+ q(\mathbf{v})$  ?

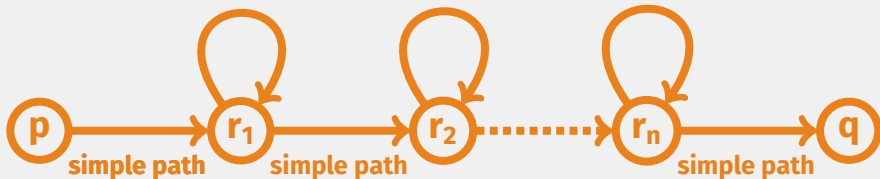
## Theorem

$$p(\mathbf{u}) \xrightarrow{*}_{\mathbb{Q}_+} q(\mathbf{v})$$

is expressible in  $\exists \text{FO}(\mathbb{Q}, +, <)$



# Continuous VASS: logical characterization

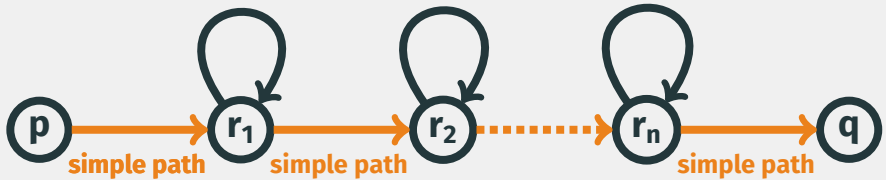


## Theorem

$$p(\mathbf{u}) \xrightarrow{*}_{\mathbb{Q}_+} q(\mathbf{v})$$

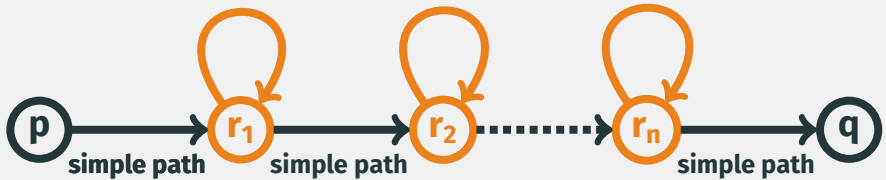
is expressible in  $\exists \text{FO}(\mathbb{Q}, +, <)$

## Continuous VASS: logical characterization



Fixed length runs are  
easy to express in  $\exists\text{FO}(\mathbb{Q}, +, <)$


# Continuous VASS: logical characterization



$$r(\mathbf{x}) \xrightarrow{*} \mathbb{Q}_+ r(\mathbf{y})$$

# Continuous VASS: logical characterization

*Equivalent*

$$r(\mathbf{x}) \xrightarrow{*} \mathbb{Q}_+ r(\mathbf{y})$$


$$r(\mathbf{x}) \xrightarrow{*} \mathbb{Q} r(\mathbf{y})$$

$$\wedge r(\mathbf{x}) \xrightarrow{*} \mathbb{Q}_+ r(\_)$$

$$\wedge r(\_) \xrightarrow{*} \mathbb{Q}_+ r(\mathbf{y})$$

## Characterization of admissible paths



$$r(\mathbf{x}) \xrightarrow{*} \mathbb{Q} \quad r(\mathbf{y})$$

$$\wedge r(\mathbf{x}) \xrightarrow{*} \mathbb{Q}_+ \quad r(-)$$

$$\wedge r(-) \xrightarrow{*} \mathbb{Q}_+ \quad r(\mathbf{y})$$

Next slide



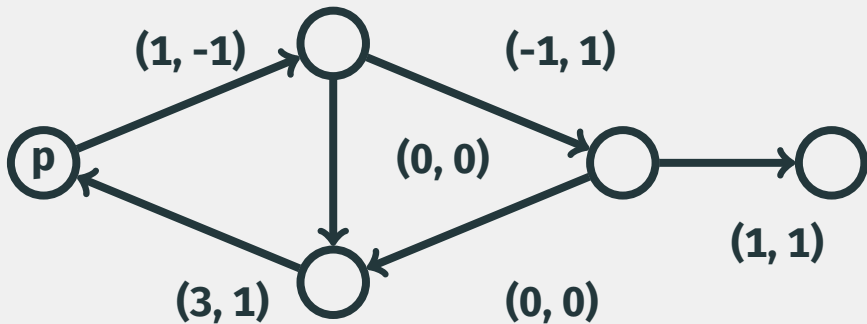
$$r(\mathbf{x}) \xrightarrow{*} \mathbb{Q} \quad r(\mathbf{y})$$

$$\wedge \quad r(\mathbf{x}) \xrightarrow{*} \mathbb{Q}_+ \quad r(\_)$$

$$\wedge \quad r(\_) \xrightarrow{*} \mathbb{Q}_+ \quad r(\mathbf{y})$$

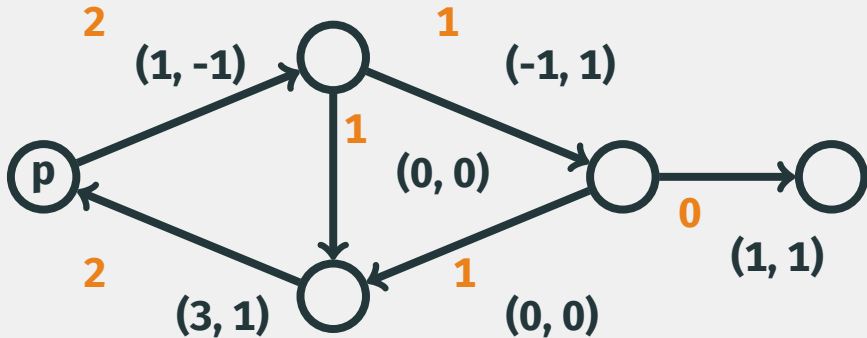
$$p(\mathbf{u}) \xrightarrow{*} \mathbb{Q} p(\mathbf{v})?$$

$$p(0, 0) \xrightarrow{*} \mathbb{Q} p(6, 0)?$$

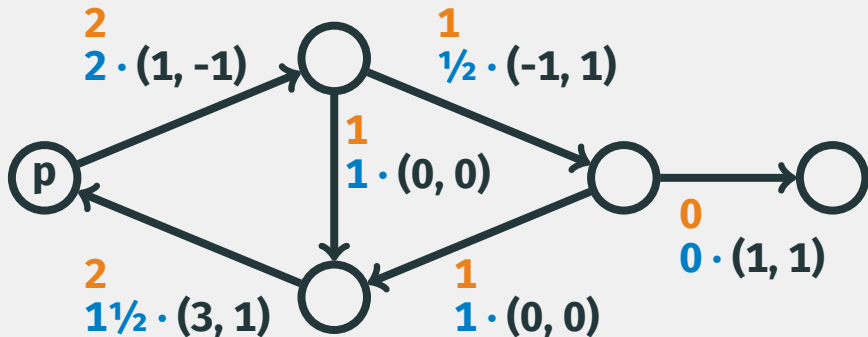




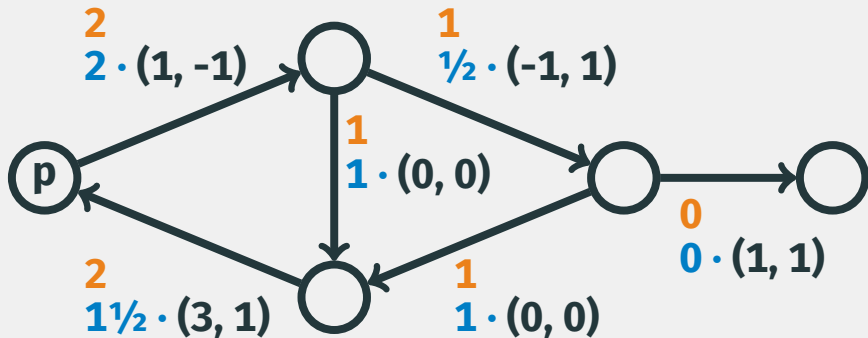
## Guess transitions occurrences



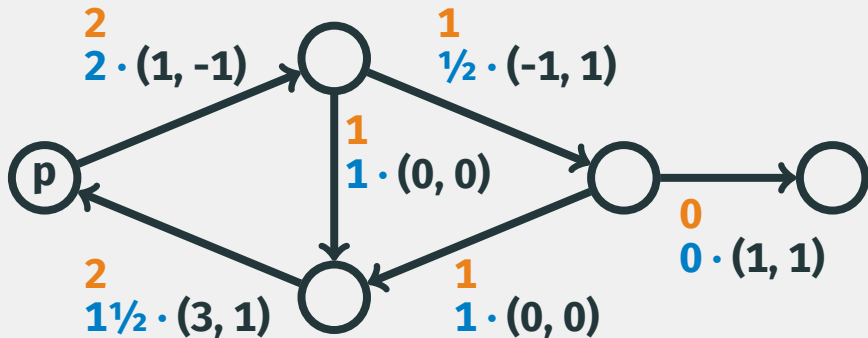
## Guess scaling factors



occurrences  $\geq$  scaling

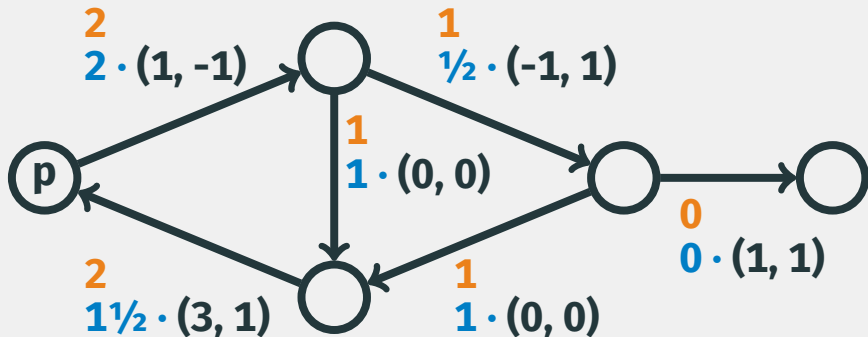


occurrences  $> 0 \iff$  scaling  $> 0$

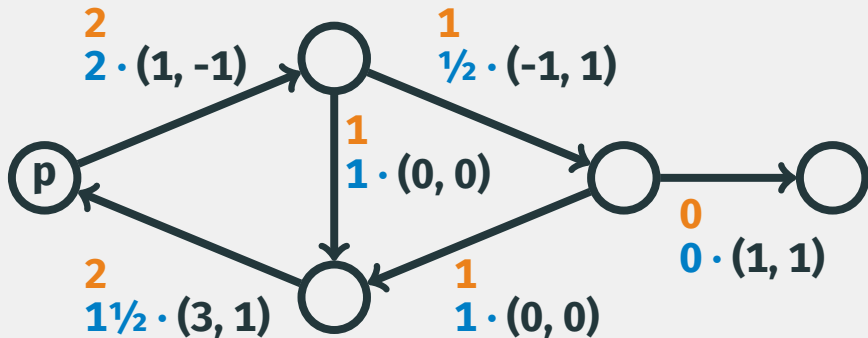


## VASS cyclic $\mathbb{Q}$ -reachability

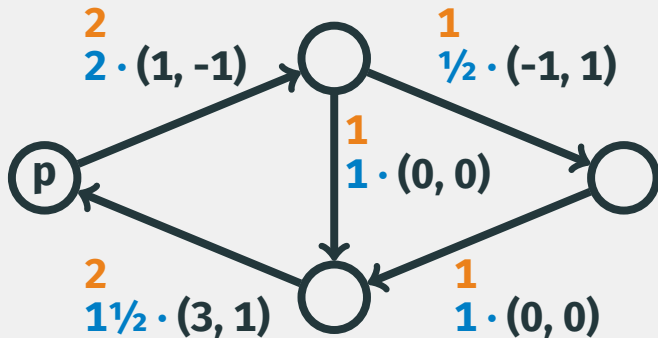
$$(0, 0) + \sum_{t \in T} \mathbf{f}_t \cdot \mathbf{z}_t = (6, 0)$$



$G[\mathbf{x}_t > 0]$  strongly connected

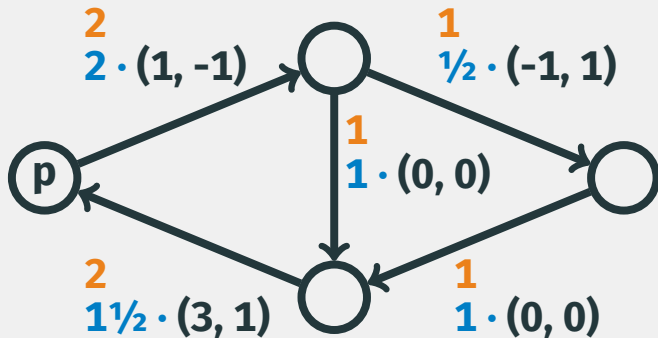


$G[\mathbf{x}_t > 0]$  strongly connected



## VASS cyclic $\mathbb{Q}$ -reachability

$$\sum_{t \in \text{in}(q)} \mathbf{x}_t = \sum_{t \in \text{out}(q)} \mathbf{x}_t$$





## Theorem

These conditions are expressible as  
convex linear Horn constraints

## Corollary

VASS cyclic  $\mathbb{Q}$ -reachability is in PTIME

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convex linear Horn constraints

## Corollary

VASS cyclic  $\mathbb{Q}$ -reachability is in PTIME

## Conclusion: summary

- new PTIME fragment of  $\exists \text{FO}(\mathbb{Q}, +, <)$
- logical characterization of  
continuous Petri nets
- new hybrid model: continuous VASS
- characterization of  $\exists \text{FO}(\mathbb{Q}, +, <)$

## Conclusion: future work

- optimization of continuous Petri nets  
w.r.t. to linear objective functions  
(e.g. constant-rate multi-mode systems of Alur *et al.* HSCC'12)
- games on continuous Petri nets  
(e.g. Minkowski games of Le Roux *et al.* STACS'17)
- more succinct encoding of  
continuous VASS reachability

**Thank you!**

**Takk fyrir!**